

Global output convergence for delayed recurrent neural networks under impulsive effects*

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ABSTRACT

In this paper, we investigate convergence of state output for a class of delayed recurrent neural networks with impulsive effects. Based on properties of time-varying inputs and monotonicity of activation function, we establish some sufficient conditions to guarantee output convergence of the networks in which state variable subjected to impulsive displacements at fixed moments of time.

Keywords : Output convergence; Recurrent neural networks; Delays; Impulse

1 INTRODUCTION

THE model of a class of recurrent neural networks (RNNs) without linear decay term is described by

$$\frac{dx_i(t)}{dt} = \sum_{j=1}^n w_{ij} g_j(x_j(t)) + u_i(t), \quad x_i(0) = x_{i0},$$

$$i \in \mathbf{N} := \{1, 2, \dots, n\}$$

The above RNNs is quite different from well-known Hopfield-type networks which show important applications in optimization [7,8]. However, in other optimization applications, convergence behavior of output space would be required, e.g., [5,6]. Under the time-varying thresholds, Liu et al. [1] and Hu et al.[2] discussed some sufficient conditions to guarantee global output convergence of this class of networks. With monotonicity and globally Lipschitz assumptions posed on activation functions, Zhang et al. [3] derived global output convergence criteria for the following RNNs with time-varying delays

$$\frac{dx_i(t)}{dt} = \sum_{j=1}^n [w_{ij} g_j(x_j(t)) + w_{ij}^r g_j(x_j(t - \tau_{ij}(t)))] + u_i(t),$$

$$i \in \mathbf{N}.$$

Along this direction, Liang et al. [4] continued to consider a class of RNNs described by integro-different equations

$$\frac{dx_i(t)}{dt} = \sum_{j=1}^n [w_{ij} g_j(x_j(t)) + w_{ij}^r \int_{-\infty}^t k_{ij}(t-s) g_j(x_j(s)) ds] + u_i(t),$$

$$i \in \mathbf{N}.$$

To the best of authors' knowledge, few authors reported output convergent dynamics of neural networks with

impulses. In this paper, we consider a class of RNNs with delays and impulses described by

$$\begin{cases} \frac{dx_i(t)}{dt} = \sum_{j=1}^n [w_{ij} g_j(x_j(t)) + w_{ij}^r g_j(x_j(t - \tau))] + u_i(t), t \neq t_k, t \geq t_0 \\ \Delta x_i(t) = I_k(t, x_i(t^-)), t \in \mathbf{P} := \{t_k | k \in \mathbf{Z}^+\} \end{cases} \quad (1)$$

where $i \in \mathbf{N}$, each $x_i(t)$ denotes the state of neuron

i , $W = (w_{ij})_{n \times n}$ and $W^r = (w_{ij}^r)_{n \times n}$ are constant connection weights, τ is the time-varying delays with upper bound by τ , the inputs $u_i(t)$ ($i \in \mathbf{N}$) are some continuous functions defined on $[t_0, +\infty)$,

$g_i(\cdot)$ ($i \in \mathbf{N}$) are networks' output activation functions. We call $x(t) = (x_1(t), \dots, x_n(t))^T$ the state of the networks at time t and call $G(x(t)) = (g_1(x_1(t)), \dots, g_n(x_n(t)))^T$ the output of the networks. Usually, the fixed impulsive instants satisfy with $t_1 < t_2 < \dots$ and $\lim_{k \rightarrow +\infty} t_k = +\infty$. This paper studies the output convergence of recurrent neural networks with impulses and time-varying inputs. Several sufficient conditions will be established for RNNs (1) to be globally output convergent.

Without otherwise statement, in this paper, we assume that

2 IMPULSIVE OUTPUT CONVERGENCE

Without otherwise statement, in this paper, we assume that

(A₁) There exist positive constant ℓ_j^\perp and ℓ_j^u such that $\ell_j^\perp \leq \frac{g_j(u) - g_j(v)}{u - v} \leq \ell_j^u$ for any $u, v \in \square$ and $u \neq v, j \in \mathbf{N}$.

(A₂) There exists a constant vector $u \in \square^n$ such that $\lim_{t \rightarrow +\infty} u(t) = u$ where $u(t) = (u_1(t), \dots, u_n(t))^T$.

Let $C = C([- \tau, 0], \mathbf{R}^n)$ be the Banach space of bounded and continuous functions. For simplicity, let $\Xi := \{x \in \square^n \mid (W + W^T)g(x) + u = 0\}$. We assume that $\Xi \neq \emptyset$, i.e., there exists at least one constant vector $x^* \in \square^n$ such that $(W + W^T)g(x^*) + u = 0$. Let $z(t) = x(t) - x^*$, $\hat{u}(t) = u(t) - u$ and $f(z(t)) = g(z(t) + x^*) - g(x^*)$, then RNNs(1) can be written as

$$\begin{cases} \frac{dz_i(t)}{dt} = \sum_{j=1}^n [w_{ij}^r f_j(z_j(t)) + w_{ij}^r f_j(z_j(t-\tau))] + \hat{u}_i(t), & t \in \mathbf{P}, t \geq t_0 \\ \Delta z_i(t) = H_k(t, z_i(t^-)), & t \in \mathbf{P} \end{cases} \quad (2)$$

where $H_k(t, z_i(t^-)) = I_k(t, z_i(t^-) + x_i^*)$, $t \in \mathbf{P}$ and $i \in \mathbf{N}$.

Definition 1 The RNNs (1) is globally output convergent if, for any $\psi \notin C$, there exists a $x^* \in \Xi$ such that $\lim_{t \rightarrow +\infty} g(x(t, \psi)) = g(x^*)$.

Remark 1 Due to the boundedness and squashing effects of activation function $g(\cdot)$, output convergence of RNNs (1) does not imply the state convergence [3]. With the time-varying input $\hat{u}(t)$ and the lack of a linear decay term, output convergence of RNNs (1) will be complete different from equilibrium-type stability [10].

In this section, we will show that, under impulsive effects, RNNs[1] is globally output convergent. Firstly, we introduce the following assumption:

(A₃) There exists a sequence $\{\beta_k\}_1^{+\infty}$ with $\beta_k > 0$ and $\sum_{k=1}^{\infty} \beta_k < +\infty$ such that

$$\sup_{t \in \mathbf{R}} \left| 1 + \frac{H_k(t, s)}{s} \right| \leq \min_{i \in \mathbf{N}} \left\{ \frac{\sqrt{\ell_i^\perp (1 + \beta_k)}}{\ell_i^\perp} \right\}$$

hold for all $k \in \mathbf{Z}^+$ and $\forall s \in \mathbf{R}$.

Remark 2 Consider special case for (A₃). As $H_k(t, s) = H_k(s)$ and $\min_{i \in \mathbf{N}} \left\{ \sqrt{\ell_i^\perp (1 + \beta_k)} / \ell_i^\perp \right\} \leq 1$.

Let $\tilde{H}_k(s) := s + H_k(s)$. Then, impulsive jumps characterized by $\tilde{H}_k(s)$ satisfy sublinear estimation $\sum_{i=1}^n \tilde{H}_k(|z_i(\cdot)|) \leq \tilde{H}_k \sum_{i=1}^n (|z_i(\cdot)|)$ which should be satisfied in [9]. In fact, state jumps $|z_i(t_k)| = \tilde{H}_k(z_i(t_k^-)) \leq e_k |z_i(t_k^-)|$ with small magnitudes $0 < e_k < 1$ have been widely employed in [10,11,12].

Lemma 1 Under assumption (A₃), for each $i \in \mathbf{N}$, the following inequality

$$f_i(s + H_k(t, s))^2 \leq (1 + \beta_k) f_i(s)^2$$

holds for $k \in \mathbf{Z}^+$, $t \in \mathbf{P}$ and $\forall s \in \mathbf{R}$.

Proof: It follows from (A₁) that

$$\forall u \in \mathbf{R}, \begin{cases} u f_i(u) \ell_i^\perp \leq f_i(u)^2 \leq u f_i(u) \ell_i^u \\ u^2 \ell_i^\perp \leq u f_i(u) \leq u^2 \ell_i^u \end{cases}$$

holds for each $i \in \mathbf{N}$. Hence, we have

$$f_i(s + H_k(t, s))^2 \leq \ell_i^u (s + H_k(t, s)) f_i(s + H_k(t, s)) \leq (\ell_i^u)^2 (s + H_k(t, s))^2$$

Assumption (A₃) implies that

$$\sup_{t \in \mathbf{R}} |s + H_k(t, s)| \leq \min_{i \in \mathbf{N}} \left\{ \frac{\sqrt{\ell_i^\perp (1 + \beta_k)}}{\ell_i^\perp} \right\} |s|$$

which leads to

$$f_i(s + H_k(t, s))^2 \leq (\ell_i^u)^2 \left(\frac{\sqrt{\ell_i^\perp (1 + \beta_k)}}{\ell_i^\perp} \right)^2 s^2 \leq (1 + \beta_k) f_i(s)^2.$$

The proof is complete.

Theorem 1 Assume (A₁) - (A₃) hold. If there exist positive constants $L_i, L_i^r, L_i^v, \tilde{\theta}_i^1$ and $\tilde{\theta}_i^2$ such that $\tilde{\theta}_i^1 + \tilde{\theta}_i^2 = 1$, $g(t) = \text{diag}(G(t)W^{(0)}, G(t)W^{(\tau)})$ is positive definite and

$$\int_{t_0}^{\infty} \hat{u}_i(s)^2 ds < +\infty$$

for each $i \in \mathbf{N}$, where

$$\begin{cases} W^{(0)} = \text{diag}(w_{ij}^0), & W^{(\tau)} = \left(\frac{1}{2L_i} |w_{ij}^{(\tau)}| \right), & G(t) = \text{diag}(D^+ g_i(z_i(t))), \\ w_{ii}^0 = w_{ii}^0 \tilde{\theta}_i^1 + \sum_{j \neq i} \frac{L_i}{2} |w_{ij}^0| + \sum_{j=1}^n \frac{L_i^r}{2} |w_{ij}^r| + \frac{L_i^v}{2}, & w_{ii}^0 = \frac{1}{2L_i} |w_{ij}^0|, & i \neq j, \end{cases}$$

Then RNNs (1) is globally output convergent.

Proof: Consider a candidate Lyapunov function

$$V(t) = \frac{1}{2} \sum_{i=1}^n f_i(z_i(t))^2. \text{ For any } k \in \mathbf{Z}^+, \text{ by}$$

calculating the derivatives of V along the trajectory of (2) for $[t_k, t_{k+1})$, we have

$$\begin{aligned} D^+V(t) &\leq \sum_{i=1}^n |f_i(z_i(t))| N_i(z(t)) \left[w_{ii} |f_i(z_i(t))| + \sum_{j \neq i} |w_{ij}| |f_j(z_j(t-\tau))| + |\hat{u}_i(t)| \right] \\ &\leq \sum_{i=1}^n N_i(z(t)) \left[w_{ii} \bar{\theta}_i^2 f_i(z_i(t))^2 + w_{ii} \bar{\theta}_i^2 f_i(z_i(t))^2 + \sum_{j \neq i} |w_{ij}| \left(L_j |f_j(z_j(t))| \times \frac{1}{L_i} |f_j(z_j(t))| \right) \right. \\ &\quad \left. + \sum_{j \neq i} |w_{ij}| \left(L_j |f_j(z_j(t))| \times \frac{1}{L_i} |f_j(z_j(t-\tau))| \right) + L_i |f_i(z_i(t))| \times \frac{1}{L_i} |\hat{u}_i(t)| \right] \\ &\leq \sum_{i=1}^n N_i(z(t)) \left[w_{ii} \bar{\theta}_i^2 f_i(z_i(t))^2 + w_{ii} \bar{\theta}_i^2 f_i(z_i(t))^2 + \sum_{j \neq i} |w_{ij}| \left(\frac{L_j}{2} f_j(z_j(t))^2 + \frac{1}{2L_i} f_j(z_j(t))^2 \right) \right. \\ &\quad \left. + \sum_{j \neq i} |w_{ij}| \left(\frac{L_j}{2} f_j(z_j(t))^2 + \frac{1}{2L_i} f_j(z_j(t-\tau))^2 \right) + \frac{L_i}{2} f_i(z_i(t))^2 + \frac{1}{2L_i} \hat{u}_i(t)^2 \right] \\ &\leq \sum_{i=1}^n N_i(z(t)) \left\{ \left[w_{ii} \bar{\theta}_i^2 + \sum_{j \neq i} \frac{L_j}{2} |w_{ij}| + \sum_{j \neq i} \frac{L_j}{2} |w_{ij}| + \frac{L_i}{2} \right] f_i(z_i(t))^2 \right. \\ &\quad \left. + \sum_{j \neq i} \frac{1}{2L_i} |w_{ij}| f_j(z_j(t))^2 + \sum_{j \neq i} \frac{1}{2L_i} |w_{ij}| f_j(z_j(t-\tau))^2 + \frac{1}{2L_i} \hat{u}_i(t)^2 + w_{ii} \bar{\theta}_i^2 f_i(z_i(t))^2 \right\} \end{aligned}$$

where $N_i(z(t)) := D^+ g_i(z_i(t))$, $i \in \mathbf{N}$. Therefore, we have

$$\begin{aligned} D^+V(t) &\leq |f(z(t))|^T G(t) W^{(0)} |f(z(t))| + |f(z(t-\tau))|^T G(t) W^{(\tau)} |f(z(t-\tau))| \\ &\quad + \sum_{i=1}^n N_i(z(t)) \left[\frac{1}{2L_i} \hat{u}_i(t)^2 + w_{ii} \bar{\theta}_i^2 f_i(z_i(t))^2 \right] \\ &\leq (|f(z(t))|^T, |f(z(t-\tau))|^T) g(t) (|f(z(t))|^T, |f(z(t-\tau))|^T)^T \\ &\quad + \sum_{i=1}^n N_i(z(t)) \left[\frac{1}{2L_i} \hat{u}_i(t)^2 + w_{ii} \bar{\theta}_i^2 f_i(z_i(t))^2 \right] \\ &\leq \sum_{i=1}^n N_i(z(t)) w_{ii} \bar{\theta}_i^2 f_i(z_i(t))^2 + \sum_{i=1}^n \frac{\ell_i}{2L_i} \hat{u}_i(t)^2. \end{aligned} \tag{3}$$

It follows from that Lemma 1 that

$$\begin{aligned} |V(t_k) - V(t_k^-)| &= \frac{1}{2} \sum_{i=1}^n |f_i(z_i(t_k))^2 - f_i(z_i(t_k^-))^2| \\ &\leq \frac{1}{2} \sum_{i=1}^n |f_i(z_i(t_k^-)) + H_k(t_k, z_i(t_k))^2 - f_i(z_i(t_k^-))^2| \\ &\leq \frac{\beta_k}{2} \sum_{i=1}^n f_i(z_i(t_k^-))^2 \\ &= \beta_k V(t_k^-). \end{aligned} \tag{4}$$

Integrating both sides of (3) from t_0 to t and using (4), we get

$$\begin{aligned} V(t) &\leq V(t_0) + \int_{t_0}^t \sum_{i=1}^n N_i(z(s)) w_{ii} \bar{\theta}_i^2 f_i(z_i(s))^2 \\ &\quad + \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^t \hat{u}_i(s)^2 ds + \sum_{t_0 < t_k \leq t} [V(t_k) - V(t_k^-)] \\ &\leq V(t_0) + \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^t \hat{u}_i(s)^2 ds + \sum_{t_0 < t_k \leq t} \beta_k V(t_k^-). \end{aligned} \tag{5}$$

Suppose $\mathbf{P}\hat{\mathbf{a}}(t_0, t] = \{t_{m_1}, t_{m_2}, \dots, t_{m_l}\}$ and

$m_z = m_{z-1} + 1$, $z = 2, 3, \dots, l$. We assert that

$$V(t) \leq \beta \left[V(t_0) + \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^t \hat{u}_i(s)^2 ds \right],$$

where $\beta = \prod_{k=1}^{+\infty} (1 + \beta_k) \in [1, +\infty)$. (6)

In fact, as $t_0 < t < t_{m_1}$, it follows from (5) that

$$\begin{cases} V(t) \leq V(t_0) + \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^t \hat{u}_i(s)^2 ds, \\ V(t_{m_1}^-) \leq V(t_0) + \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^{t_{m_1}^-} \hat{u}_i(s)^2 ds \end{cases} \tag{7}$$

As $t_{m_1} \leq t < t_{m_2}$, it follows from (5) and (7) that

$$\begin{cases} V(t) \leq V(t_0) + \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^t \hat{u}_i(s)^2 ds + \beta_{m_1} V(t_{m_1}^-) \\ \leq (1 + \beta_{m_1}) V(t_0) + (1 + \beta_{m_1}) \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^t \hat{u}_i(s)^2 ds, \\ V(t_{m_2}^-) \leq (1 + \beta_{m_1}) V(t_0) + (1 + \beta_{m_1}) \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^{t_{m_2}^-} \hat{u}_i(s)^2 ds \end{cases} \tag{8}$$

As $t_{m_2} \leq t < t_{m_3}$, it follows from (5), (7) and (8) that

$$\begin{cases} V(t) \leq V(t_0) + \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^t \hat{u}_i(s)^2 ds + \beta_{m_1} V(t_{m_1}^-) + \beta_{m_2} V(t_{m_2}^-) \\ \leq (1 + \beta_{m_1})(1 + \beta_{m_2}) V(t_0) + (1 + \beta_{m_1})(1 + \beta_{m_2}) \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^t \hat{u}_i(s)^2 ds, \\ V(t_{m_3}^-) \leq (1 + \beta_{m_1})(1 + \beta_{m_2}) V(t_0) + (1 + \beta_{m_1})(1 + \beta_{m_2}) \sum_{i=1}^n \frac{\ell_i}{2L_i} \int_{t_0}^{t_{m_3}^-} \hat{u}_i(s)^2 ds \end{cases} \tag{9}$$

From mathematical induction argument, we can derive that

$$V(t) \leq V(t_0) \prod_{t_0 < t_k \leq t} (1 + \beta_k) + \prod_{t_0 < t_k \leq t} (1 + \beta_k) \sum_{i=1}^n \frac{\ell_i^u}{2L_i^v} \int_{t_0}^t \hat{u}_i(s)^2 ds$$

$$\leq \beta \left[V(t_0) + \sum_{i=1}^n \frac{\ell_i^u}{2L_i^v} \int_{t_0}^t \hat{u}_i(s)^2 ds \right].$$

Since $\int_{t_0}^{\infty} \hat{u}_i(s)^2 ds < +\infty$ for each $i \in \mathbf{N}$, $V(t)$ is bounded for $[t_0, +\infty)$. Hence, there exists a $\zeta_i > 0$ such that $\hat{u}_i(t) < \sqrt{\frac{\ell_i^{\perp}}{\ell_i^u} L_i^v \tilde{\theta}_i^2 |w_{ii}|} \zeta_i$ for all $t \geq s_1^*$. It follows from (3) that

$$D^+V(t) \leq \sum_{i=1}^n \ell_i^{\perp} w_{ii} \tilde{\theta}_i^2 \zeta_i + \sum_{i=1}^n \frac{\ell_i^u}{2L_i^v} \hat{u}_i(t)^2$$

$$< \frac{1}{2} \sum_{i=1}^n \ell_i^{\perp} w_{ii} \tilde{\theta}_i^2 \zeta_i < 0, \quad \forall t \geq s_1^* \tag{10}$$

Hence, $V(t)$ is nonincreasing on $[s_1^*, t_m)$ and $[t_k, t_{k+1})$ ($k \geq m$). So, $V(t) \leq V(s_1^*)$ for $s_1^* \leq t \leq t_m$ and $V(t) \leq V(t_k)$ for $t_k \leq t \leq t_{k+1}$ ($k \geq m$). The boundedness of $V(t)$ and (4) leads to the basic fact $\sum_{k=1}^{+\infty} |V(t_k) - V(t_k^-)| < +\infty$.

Let $\xi_k = \sum_{v=m}^{+\infty} |V(t_v) - V(t_v^-)|$ ($k \geq m$) and define

$H : [s_1^*, +\infty) \rightarrow \mathbf{R}$ by

$$H(t) := \begin{cases} V(t), & s_1^* \leq t < t_m \\ -\xi_k + V(t), & t_k \leq t < t_{k+1}, \quad k \geq m \end{cases} \tag{11}$$

Obviously, $\lim_{k \rightarrow +\infty} \xi_k$ exists and $H(t)$ is nonincreasing on both $[s_1^*, t_m)$ and $[t_k, t_{k+1})$ ($k \geq m$). We claim that $H(t_k) \geq H(t_{k+1})$ for $k \geq m$. In fact, for $k \geq m$, we have

$$H(t_k) = -\xi_k + V(t_k) \geq \xi_k + V(t_{k+1}^-)$$

$$\geq -\sum_{v=m}^k |V(t_v) - V(t_v^-)| - [V(t_{k+1}) - V(t_{k+1}^-)] + V(t_{k+1})$$

$$= -\sum_{v=m}^{k+1} |V(t_v) - V(t_v^-)| + V(t_{k+1})$$

$$= -\xi_{k+1} + V(t_{k+1}) = H(t_{k+1})$$

which leads to the monotonicity of $H(t)$ on $[s_1^*, +\infty)$. It is easily to see that $H(t)$ is boundedness and so $\lim_{t \rightarrow +\infty} H(t)$ exists. By (11), we

see that $\lim_{t \rightarrow +\infty} V(t) = \alpha$ exists and $\alpha \geq 0$. We claim that $\alpha = 0$. Otherwise, there exist constants $\alpha_i \geq 0$ ($i \in \mathbf{N}$) and a $i^* \in \mathbf{N}$ such that $\sum_{k=1}^n \alpha_k = \alpha$, $\lim_{t \rightarrow +\infty} \frac{f_i(z_i(t))^2}{2} = \alpha_i$ and $\alpha_{i^*} \geq 0$.

Therefore, we can see that there exists a $s_2^* > s_1^*$ such that $\forall t > s_2^*$

$$f_i(z_i(t))^2 \geq \frac{\alpha_i}{2} \quad \text{and} \quad \hat{u}_i(t)^2 \leq \frac{\alpha}{2} \tilde{\theta}_i^2 |w_{ii}| L_i^v$$

It follows from (3) that $\forall t > s_2^*$

$$D^+V(t) \leq \sum_{k=1}^n N_i(z(t)) \frac{\tilde{\theta}_i^2}{4} w_{ii} \alpha_i$$

Integrate above inequality from s_2^* to t , we get

$$V(t) \leq V(s_2^*) + \sum_{k=1}^n \frac{\tilde{\theta}_i^2}{4} w_{ii} \alpha_i \int_{s_2^*}^t N_i(z(s)) ds + \sum_{s_2^* \leq t_k \leq t} [V(t_k) - V(t_k^-)]$$

$$\leq V(s_2^*) + \sum_{k=1}^n \frac{\tilde{\theta}_i^2}{4} w_{ii} \alpha_i \int_{s_2^*}^t N_i(z(s)) ds + \sum_{s_2^* \leq t_k \leq t} \beta_k V(t_k^-)$$

$$\leq \prod_{s_2^* \leq t_k < t} (1 + \beta_k) \left[V(s_2^*) + \sum_{k=1}^n \frac{\tilde{\theta}_i^2}{4} w_{ii} \alpha_i \int_{s_2^*}^t N_i(z(s)) ds \right]$$

$$\leq \beta \left[V(s_2^*) + \sum_{k=1}^n \frac{\tilde{\theta}_i^2}{4} w_{ii} \alpha_i \int_{s_2^*}^t N_i(z(s)) ds \right]$$

which leads to

$$V(t) \leq \beta \left[V(s_2^*) + \sum_{k=1}^n \frac{\tilde{\theta}_i^2}{4} w_{ii} \alpha_i \ell_i^{\perp} (t - s_2^*) \right] \rightarrow -\infty$$

as $t \rightarrow +\infty$.

This contradicts to $V(t) \geq 0$. Based on above analysis, we have show that $\alpha = 0$. Hence $\lim_{t \rightarrow +\infty} f_i(z_i(t)) = 0$ and the output vector of (2) is globally output convergent.

For any given constant $r > 1$ and each $k \in \mathbf{Z}^+$, define $S_r := \{x \in \mathbf{R} : |x| < r\}$ and $H_k : \mathbf{R} \times S_r \rightarrow S_r$. We make the following assumption :

$(\hat{A}_3) H_k(t, s) \in \mathbf{C}^1(\mathbf{R} \times \mathbf{S}_r, \mathbf{S}_r)$ and there exists a

$\rho_k \in (0, 1)$ such that $\sup_{t \in \rho} \frac{\partial H_k(t, s)}{\partial s} \leq \rho_k - 1$,

$s \in \mathbf{S}_r$ holds for $k \in \mathbf{R}^+$.

For each $k \in \mathbf{Z}^+$, the function $F_k(s) := s + H_k(t_k, s)$ has the following property, which will be used when we prove output convergence of RNNs (2).

Lemma2 For each $k \in \mathbf{Z}^+$, $F_k(s) := s + H_k(t_k, s)$ maps bounded sets of \mathbf{S}_r into bounded sets of \mathbf{S}_r .

Moreover, $|F_k(\hat{r})| \leq \rho_k |r|$ holds for any $\hat{r} \in \mathbf{S}_r$ and $k \in \mathbf{Z}^+$.

Proof: It follows from (\hat{A}_3) that

$$\frac{dF_k(s)}{ds} - 1 \leq \sup_{t \in \rho} \frac{\partial H_k(t, s)}{\partial s} \leq \rho_k - 1.$$

Together with $F_k(0) = 0$ ($k \in \mathbf{Z}^+$), for any $\hat{r} \in [-r, r]$, we have

$$\int_0^{\hat{r}} \frac{dF_k(s)}{ds} \leq \rho_k |\hat{r}| \Rightarrow |F_k(\hat{r})| \leq \rho_k |r| < r$$

Thus, for any bounded set $E \in \mathbf{S}_r$, $F_k(E) \in \mathbf{S}_r$. This complete the proof.

Theorem 2 Assume that $(A_1) - (A_2)$ and (\hat{A}_3) hold. If

$$\ell_i^1 > 0 \text{ and } \sum_{i=1, i \neq j}^n \ell_i^u |w_{ii}| > w_{ii}^l \ell_i^1 + \sum_{j=1}^n |w_{ij}^r| \ell_j^u \quad (12)$$

holds for all $j \in \mathbf{N}$ and there exist constants $\delta_i > 0$, $v > 0$ such that

$$\ln \rho_{k+1} + \int_{t_i}^{t_{i+1}} \left[\frac{m^\tau (\frac{v}{2} + \varepsilon) + m(\varepsilon - \frac{v}{2})}{v - \varepsilon} \right] ds \leq -\delta_{i+1} \quad (13)$$

where $\sum_{i=1}^{+\infty} \delta_i = +\infty$ and

$$m = \min_{j \in \mathbf{N}} \left\{ -w_{ii} \ell_i^1 + \sum_{i=1, i \neq j}^n \ell_i^u |w_{ii}| \right\},$$

$$m^\tau = \max_{j \in \mathbf{N}} \left\{ \sum_{i=1}^n |w_{ii}^r| \ell_j^u \right\}$$

Then RNNs (2) is globally output convergent.

Proof: Define a candidate Lyapunov function

$V(t) = \sum_{i=1}^n |z_i(t)|$ for all $t \geq t_0$. Then we get

$$D^+V(t) \leq \sum_{i=1}^n \left[w_{ii}^l \ell_i^1 |z_i(t)| + \sum_{j \neq i} |w_{ij}| \ell_j |z_j(t)| + \sum_{j=1}^n |w_{ij}^r| \ell_j |z_j(t-\tau)| + |\hat{u}_i(t)| \right]$$

$$\leq \sum_{i=1}^n \left[\sum_{j=1}^n m_{ij} |z_j(t)| + \sum_{j=1}^n m_{ij}^\tau |z_j(t-\tau)| + |\hat{u}_i(t)| \right]$$

$$\leq \sum_{j=1}^n \left(\sum_{i=1}^n m_{ij} \right) |z_j(t)| + \sum_{j=1}^n \left(\sum_{i=1}^n m_{ij}^\tau \right) |z_j(t-\tau)| + \sum_{i=1}^n |\hat{u}_i(t)|$$

$$\leq -mV(t) + m^\tau V(t-\tau) + \hat{u}(t), t \in [t_k, t_{k+1}) \quad (14)$$

where $\hat{u}(t) = \sum_{i=1}^n |u_i(t)|$. It follows from (12) that

$m > m^\tau$. Since $\hat{u}(t) \rightarrow 0$ as $t \rightarrow +\infty$, there exists a constant $\delta > 0$ such that $\hat{u}(t) < \delta$ for all $t \geq t_0$. For any given

$H > \max \left\{ 1, \frac{\delta}{m - m^\tau} \right\}$, we will prove

$\sup_{t_0 - \tau \leq \theta \leq t_0} V(\theta) \leq H$ imply $V(t) \leq H$ for all

$t \geq t_0$. Otherwise, there is a $s_1^* > t_0$ with $s_1^* \in [t_0, t_1)$ or $s_1^* \in [t_k, t_{k+1})$, $k \geq 1$ such that

$D^+V(s_1^*) > 0$, $V(s_1^*) > H$, $V(t) \leq H$ for $t_0 - \tau \leq t < s_1^*$. As $s_1^* \in [t_0, t_1)$, it follows from

(14) that $D^+V(t) \leq -mH + m^\tau H + \delta \leq 0$. This is a contradiction and it shows that $V(t) \leq H$ for

all $t \in [t_0 - \tau, t_1)$. As $s_1^* \in [t_1, t_2)$, due to

$V(t_1) \leq \rho_1 \sup_{t_0 - \tau \leq \theta \leq t_1^-} V(\theta) \leq H$, it follows from (14)

that $D^+V(t) \leq -mH + m^\tau H + \delta \leq 0$. This is a contradiction. Thus, $V(t) \leq H$ for all

$t \in [t_0 - \tau, t_2)$. By similar argument, we can show that $V(t) \leq H$ for all $t \in [t_0 - \tau, t_k)$ for

$k \in \mathbf{Z}^+$. Therefore, $V(t) \leq H$ for all $t \geq t_0 - \tau$. Let $v := \limsup_{t \rightarrow +\infty} V(t) \geq 0$.

Next, we will prove that $v = 0$. If it is not true, i.e., $v > 0$, we will prove it leads to a contradiction.

By $\lim_{t \rightarrow +\infty} \hat{u}(t) = 0$, there must exists a $s_2^* > t_0$ such

that $\hat{u}(t) \leq \frac{v(m-m^\tau)}{2}$ for all $t \geq s_2^*$. Choose a

$\varepsilon > 0$ such that $0 < \varepsilon < \frac{m-m^\tau}{2(m+m^\tau)}$. By

$\limsup_{t \rightarrow +\infty} V(t) = v$, there exists a $s_3^* \geq s_2^*$ such that

$\sup_{t-\tau \leq \theta \leq t} V(\theta) \leq v + \varepsilon$ for all $t > s_3^*$. We assert that

there exists a $s_4^* \geq s_3^*$ such that

$$D^+V(t) \leq 0, \quad \forall t \geq s_4^*. \quad (15)$$

Otherwise, there must exist a $s_5^* \geq s_3^*$ such that $D^+V(s_5^*) > 0$ and $V(s_5^*) \geq v - \varepsilon$. However, from (14), we have

$$D^+V(t) \leq -m(v-\varepsilon) + m^\tau(v+\varepsilon) + \frac{v(m-m^\tau)}{2} \\ = (m^\tau - m)v + (m^\tau + m)\varepsilon \leq 0$$

which is a contradiction. This proves that (15) is true, i.e., $V(t)$ is nonincreasing on $[s_4^*, t_m)$ and $[t_k, t_{k+1})$, $k \geq m$. Together with (15), we get that $V(t_k) \geq V(t_{k+1}^-)$ for $k \in \mathbf{Z}^+$. Hence, $\{V(t_k)\}$ is bounded and nonincreasing, $\lim_{k \rightarrow \infty} V(t_k) = v$. There exist a $s_6^* \geq s_4^*$ such that $V(t) > v - \varepsilon$ and hence

$$D^+V(t) \leq -mV(t) + m^\tau(v+\varepsilon) + \frac{v}{2}(m-m^\tau) \text{ for all}$$

$t \geq s_6^*$ which leads to

$$\int_{V(t_k)}^{V(t_{k+1}^-)} \frac{ds}{s} \leq \int_{t_k}^{t_{k+1}} \left[-m + \frac{m^\tau(v+\varepsilon) + \frac{v}{2}(m-m^\tau)}{V(s)} \right] ds \\ \leq \int_{t_k}^{t_{k+1}} \left[-m + \frac{m^\tau(v+\varepsilon) + \frac{v}{2}(m-m^\tau)}{v-\varepsilon} \right] ds. \quad (16)$$

For any $s \in \mathbf{S}_H$, it follows from Lemma 2 that $F_k(s) \in [-\rho_k |s|, \rho_k |s|]$. So, we get

$$V(t_{k+1}) = \sum_{i=1}^n |z_i(t_{k+1}^-) + H_{k+1}(t_{k+1}, z_i(t_{k+1}^-))| \\ \leq \sum_{i=1}^n \rho_{k+1} |z_i(t_{k+1}^-)| \\ = \rho_{k+1} V(t_{k+1}^-)$$

Together with (16), we can get that

$$\int_{V(t_k)}^{V(t_{k+1})} \frac{ds}{s} \leq \int_{V(t_{k+1}^-)}^{V(t_{k+1})} \frac{ds}{s} + \int_{t_k}^{t_{k+1}} \left[-m + \frac{m^\tau(v+\varepsilon) + \frac{v}{2}(m-m^\tau)}{v-\varepsilon} \right] ds \\ \leq \int_{V(t_{k+1}^-)}^{\rho_{k+1}V(t_{k+1}^-)} \frac{ds}{s} + \int_{t_k}^{t_{k+1}} \left[-m + \frac{m^\tau(v+\varepsilon) + \frac{v}{2}(m-m^\tau)}{v-\varepsilon} \right] ds \\ \leq \ln \rho_{k+1} + \int_{t_k}^{t_{k+1}} \left[\frac{m^\tau(\frac{v}{2} + \varepsilon) + m(\varepsilon - \frac{v}{2})}{v-\varepsilon} \right] ds \\ \leq -\delta_{k+1}.$$

We get $V(t_{k+1}) \leq V(t_k) - (v + \varepsilon)\delta_{k+1}$ which implies that $\lim_{k \rightarrow +\infty} V(t_k) = -\infty$, a contradiction and so $v = 0$. Since $V(t) \leq V(t_k)$ for all $t \in [t_k, t_{k+1})$, it follows that $\lim_{t \rightarrow \infty} V(t) = 0$ which implies that $\lim_{t \rightarrow \infty} x(t) = 0$. The proof is complete.

3 CONCLUSIONS

In this paper, we investigate the global output convergence of a class of delayed recurrent neural networks under impulsive perturbation. Based on convergence of time-varying inputs and monotonicity of activation functions, we establish some sufficient conditions to guarantee output convergence of the networks subjected to impulsive state displacements at fixed moments of time.

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